Ken Sakurada

Department of Mechanical and Control Engineering Tokyo Institute of Technology 2-12-1 O-okayama, Meguro-ku, Tokyo, Japan

RESEARCH INTERESTS

Structure from Motion, Change Detection, Image Retrieval, Object Recognition, Machine Learning, SLAM, Autonomous Driving

EDUCATION

Carnegie Mellon University	
Visiting Scholar of Robotics Institute	04/2013-03/2014
TOHOKU UNIVERSITY	
PhD Student of Information Science	04/2011-03/2015
Master of Information Science	04/2009-03/2011
Bachelor of Mechanical Engineering	04/2005-03/2009

EMPLOYMENT

Postdoctoral Researcher,	Tokyo Institute of Technology	04/2015-present
Research Assistant,	Tohoku University	04/2014-03/2015
JSPS Research Fellow (DC2),	Tohoku University	04/2012-03/2014
Research Assistant,	Tohoku University	04/2011-03/2011

PUBLICATIONS

- Ken Sakurada, Takayuki Okatani, "Change Detection from a Street Image Pair using CNN Features and Superpixel Segmentation", BMVC2015 (Poster, Acceptance Rate: 33%)
- Ken Sakurada, Takayuki Okatani, Kris M. Kitani, "Massive City-scale Surface Condition Analysis using Ground and Aerial Imagery", ACCV2014 (Oral, Acceptance Rate: Less than 4%), "Best Application Paper Honorable Mention Award"
- Ken Sakurada, Takayuki Okatani, Koichiro Deguchi, "Detecting Changes in 3D Structure of a Scene from Multi-view Images Captured by a Vehicle-mounted Camera", CVPR2013 (Poster, Acceptance Rate: 25.2%)
- Takayuki Okatani, **Ken Sakurada**, Jun Yanagisawa, Daiki Tetsuka, Koichiro Deguchi, "Creating Multi-Viewpoint Panoramas of Streets with Sparsely Located Buildings", FSR2012
- Ken Sakurada, Eijiro Takeuchi, Kazunori Ohno, Satoshi Tadokoro, "Development of Motion Model and Position Correction Method using Terrain Information for Tracked Vehicles with Sub-Crawlers", IROS2010

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- Ken Sakurada, Shihiko. Suzuki, Kazunori. Ohno, Eeijiro. Takeuchi, Satoshi Tadokoro, Akihiko Hata, Naoki Miyahara, Kazuyuki Higashi, "Real-time Prediction of Fall and Collision of Tracked Vehicle for Remote-Control Support", SII2010, "Best Paper Award Finalist"
- Akihiko Hata, Kazunori Ohno, Eijiro Takeuchi, Satoshi Tadokoro, **Ken Sakurada**, Naoki Miyahara, Kazuyuki Higashi, "Development of a Laser Scan Method to Decrease Hidden Areas Caused by Objects Like Pole at Whole 3-D Shape Measurement", SII2010

TECHNICAL

C/C++, C#, Python, MATLAB, CUDA, OpenGL, Qt

HONORS AND AWARDS

- ACCV2014 Best Application Paper Honorable Mention Award
- Graduation Honor, Mechanical Major in Graduate School of Information Science, Tohoku University, 2010
- SII2010 Best Paper Award Finalist
- Second Place of Rescue Robot League of RoboCup World 2009 (Team: Pelican United)
- Eiji Muto Student Award, Japan Society for Design Engineering, 2008